

# Journal of Xue Gong for Spring semester 2016

May 16, 2016

## 1 January 11 - 19

This week I worked on the G2T2 case, and looked at if it is possible for  $\alpha_1 \neq \alpha_2 = \dots = \alpha_d$  and  $\alpha_2 \neq \alpha_1 = \alpha_3 = \dots = \alpha_d$  to happen.

## 2 January 20 - 26

I kept working on the G2T2 case. I tried to find more solutions to the equilibrium points to the gradient flow, but my approach was wrong.

## 3 January 27 - February 2

I continued to study the G2T2 case. And I started to edit the tensor chapter in my dissertation.

## 4 February 3 - 9

I edited the tensor chapter, and studied the saddle value  $\nu$  when  $\alpha_1 = \dots = \alpha_m \neq \alpha_{m+1} = \dots = \alpha_d$  for  $2 \leq m \leq d - 2$ .

## 5 February 10 - 16

I proved that  $\nu > 1$  when  $2 \leq m \leq d - 2$ , and related this situation to  $m = 1$ . The same results for  $m = 1$  can be found when using the formulas in the case of  $2 \leq m \leq d - 2$  and setting  $m = 1$ . So we can combine the two cases together.

## 6 February 17 - 23

I wrote the results from last week into my dissertation and made more corrections on typos and grammar mistakes.

## 7 February 24 - March 1

I submitted my dissertation to the committee members, and started to edit the dissertation according to the feedback from the committee members.

## 8 March 2 - 8

I continued to work on editing the dissertation, and also prepared for the dissertation defense.

## 9 March 9 - 15

I passed the dissertation defense on March 10. Then I did more editing of the dissertation so that it can be finally submitted. I also prepared a poster for the Pi Day poster presentations on my results in the G1T2 case of tensor approximations.

## 10 March 16 - 22

I started to look at a special G1T2 case when  $\phi = \pi/2$  and  $\alpha_1 \neq \alpha_2 = \dots = \alpha_d$ , there is a non-hyperbolic equilibrium point of the gradient flow. We want to show that this is still a saddle point.

## 11 March 23 - 29

In the G1T2 case, we know that when  $n(\vec{\alpha}) = 0$ , the regularized error function reaches its maximum,  $E_\lambda(G_1) = 1$ . In this situation,

$$\prod_{i=1}^d \cos(\alpha_i) + z \prod_{i=1}^d \cos(\alpha_i - \phi) = 0.$$

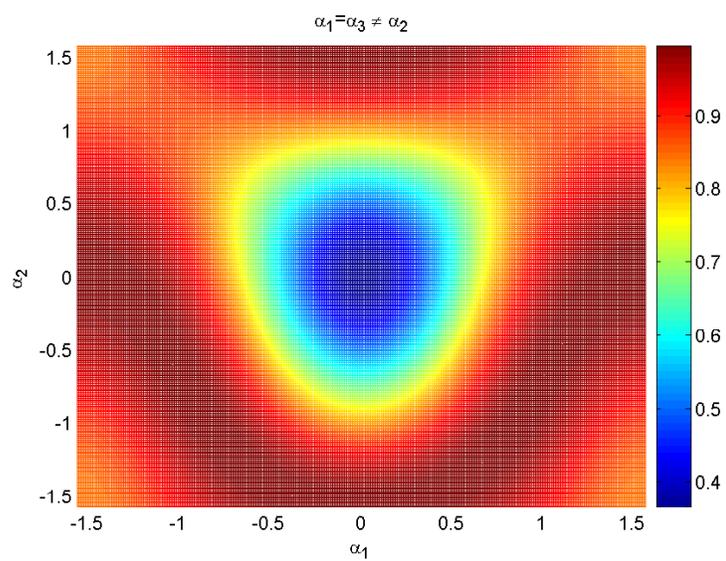
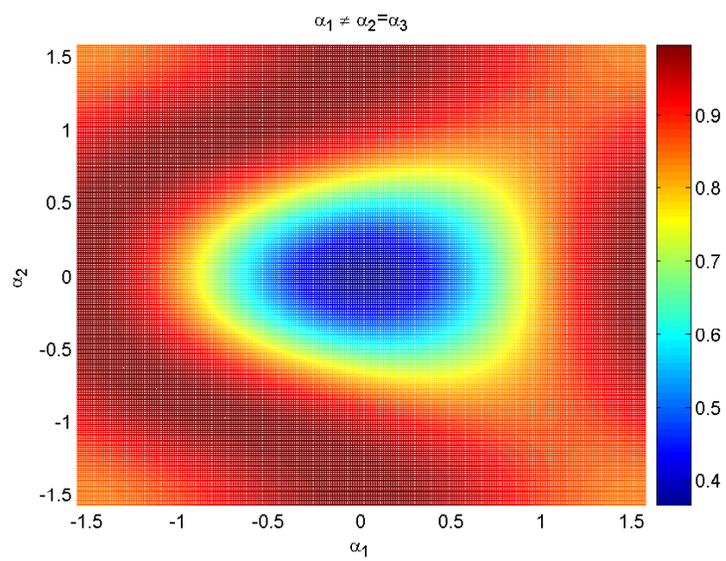
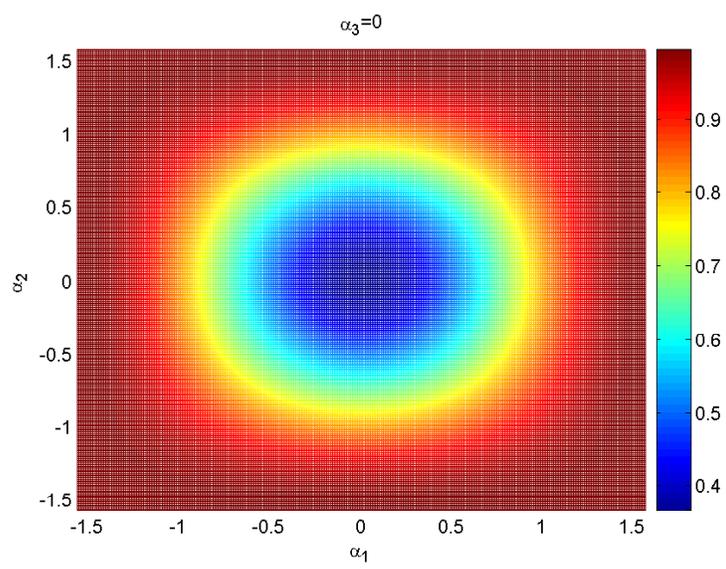
The solutions are

1.  $\alpha_i = \pi/2$  and  $\alpha_j = \phi - \pi/2$  for some  $i \neq j$ .
2. If  $\alpha_i \neq \pi/2$  for  $1 \leq i \leq d-1$  and  $\alpha_d \neq \phi - \pi/2$ , then

$$\frac{\cos(\alpha_d)}{\cos(\alpha_d - \phi)} = -z \prod_{i=1}^{d-1} \frac{\cos(\alpha_i - \phi)}{\cos(\alpha_i)}.$$

Therefore, there is a curve consisting of maximum points where  $\alpha_d$  is a function of  $\alpha_1, \dots, \alpha_{d-1}$ , given that  $\alpha_i \notin \{\pi/2, \phi - \pi/2\}$  for all  $i$  and  $z \neq 0$ .

In particular, when  $\phi = \pi/2$ , we found that this curve satisfies  $\cot(\alpha_d) = -z \prod_{i=1}^{d-1} \tan(\alpha_i)$ . For  $d = 3$ ,  $\phi = \pi/2$  and  $z = 0.5$ , we plot the error function:



## 12 March 30 - April 5

We consider the maximum points of the regularized error function as last week. In case 2 where  $\alpha_i \notin \{\pi/2, \phi - \pi/2\}$ , we have

$$\frac{\cos(\alpha_d)}{\cos(\alpha_d - \phi)} = -z \prod_{i=1}^{d-1} \frac{\cos(\alpha_i - \phi)}{\cos(\alpha_i)}. \quad (1)$$

This can be simplified as (when  $\alpha_i \neq \pi/2$  for all  $i$ )

$$\begin{aligned} & (\cos \phi)^d + \sum_{i=1}^d \tan \alpha_i (\cos \phi)^{d-1} \sin \phi + \sum_{i < j} \tan \alpha_i \tan \alpha_j (\cos \phi)^{d-2} (\sin \phi)^2 \\ & + \sum_{i < j < k} \tan \alpha_i \tan \alpha_j \tan \alpha_k (\cos \phi)^{d-3} (\sin \phi)^3 + \cdots + \prod_{i=1}^d \tan \alpha_i (\sin \phi)^d = -\frac{1}{z}. \end{aligned}$$

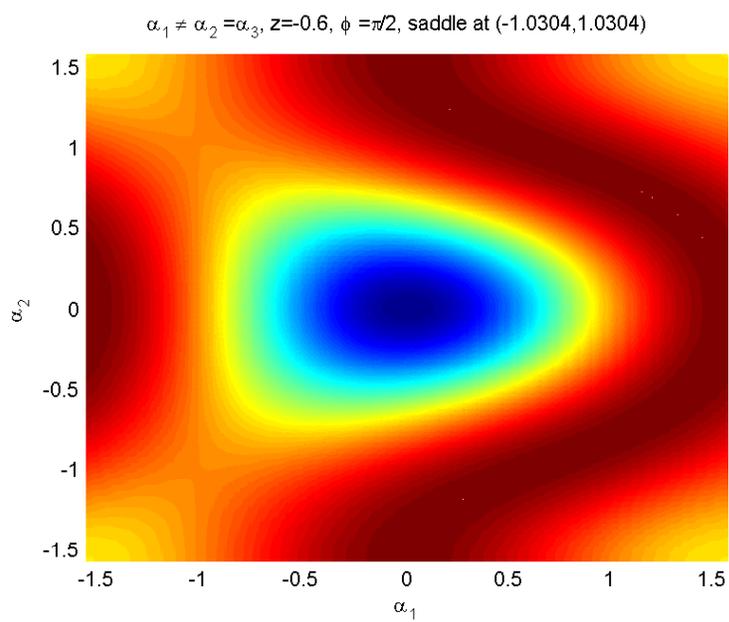
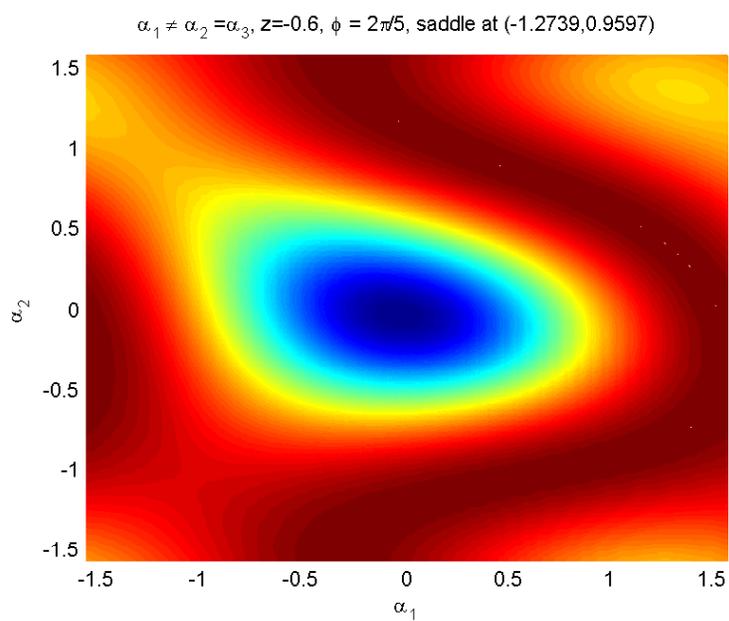
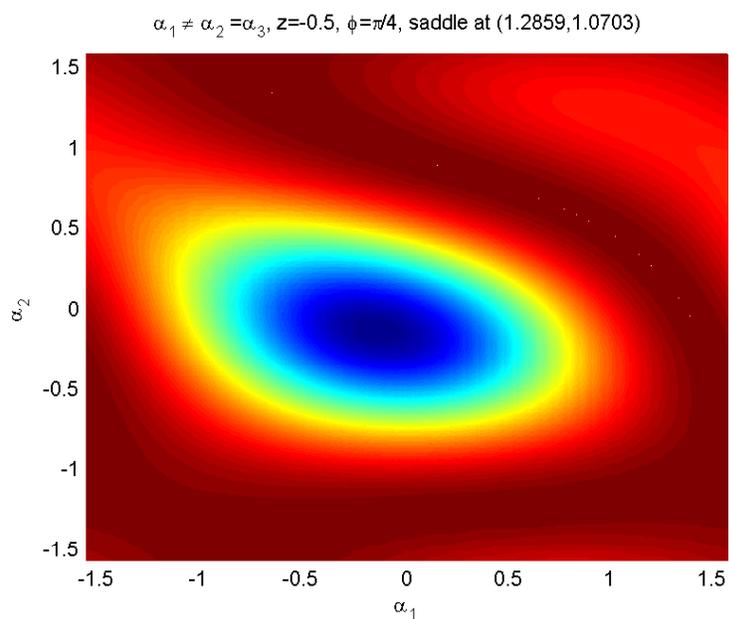
We can find that the left-hand side of (1) is one-to-one in  $(-\pi/2, \pi/2)$  because

$$\frac{\cos(\alpha_d)}{\cos(\alpha_d - \phi)} = \frac{1}{\cos \phi + \tan \alpha_d \sin \phi}.$$

Therefore, there is only one sheet of maximum points.

When  $d = 3$ , at the saddle point, there is a one-dimensional unstable manifold and a two-dimensional stable manifold. One unstable direction goes to the minimum point in the symmetric set; while the other opposite direction goes to another local minimum point on the symmetric set (the diagonal of the following plots).

When  $\phi = \pi/2$ , there is only one saddle point in the form of  $\alpha_1 \neq \alpha_2 = \alpha_3$  (three saddles considering the permutations). We see the same unstable direction even though this is a non-hyperbolic saddle.



### 13 April 6 - 12

This week, I started to put together a paper *The Optimization Landscape for Fitting a Rank-2 Tensor with a Rank-1 Tensor* with Dr. Mohlenkamp.

Because the saddle value  $\nu \in (0, \infty)$ , we map it to  $\tilde{\nu} \in (0, 1)$  by defining

$$\tilde{\nu} = \frac{\nu}{1 + \nu}.$$

In this way,  $\tilde{\nu} < \frac{1}{2}$  indicates that the strongest unstable direction is weaker than the weakest stable direction. We obtain the following figures.

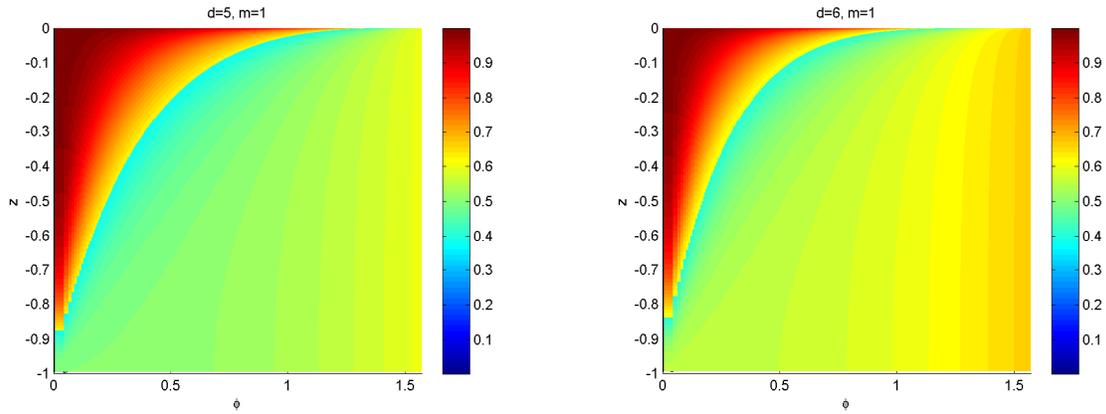


Figure 1: Plots of  $\tilde{\nu}$  when  $d = 5$  and  $d = 6$ . The saddle points satisfy  $\alpha_1 \neq \alpha_2 = \dots = \alpha_d$ .

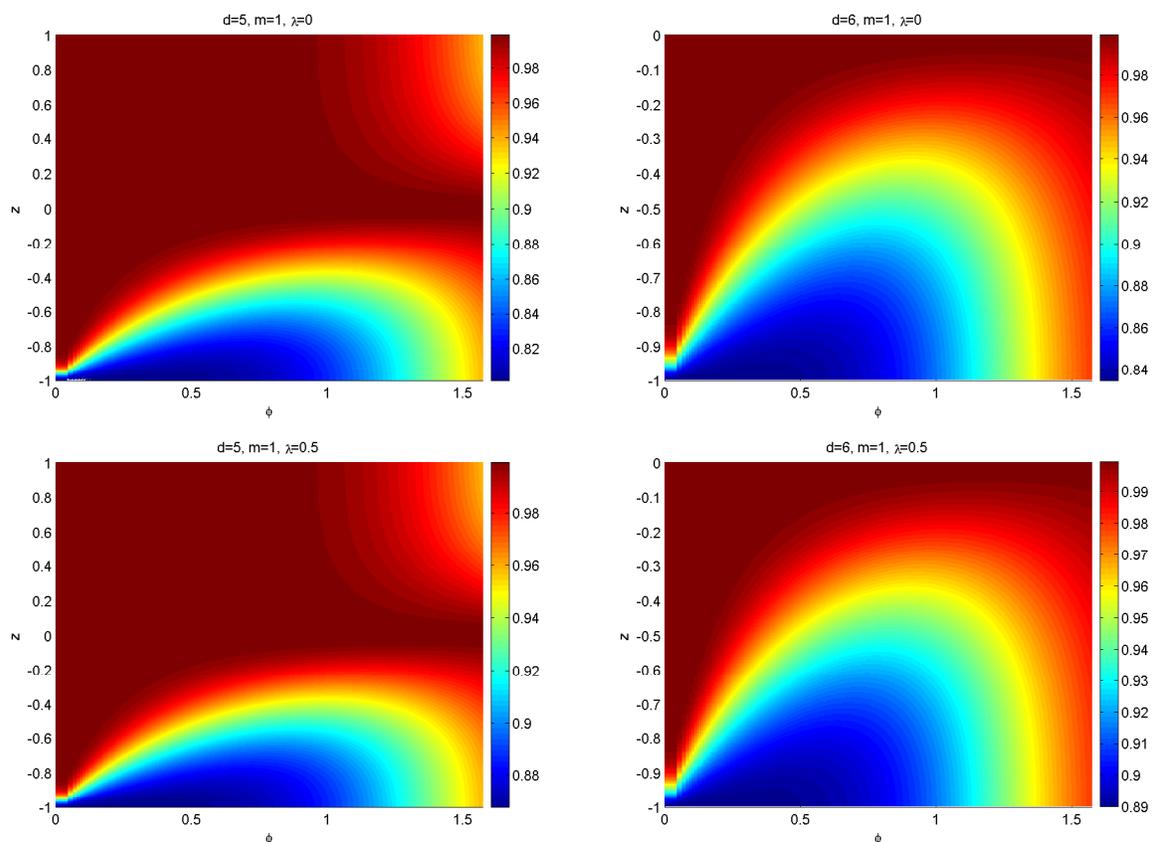


Figure 2: Plots of  $E_0(G_1)$  at the saddle points when  $d = 5$  and  $d = 6$ . The saddle points satisfy  $\alpha_1 \neq \alpha_2 = \dots = \alpha_d$ .

It looks like the errors at the saddle points are all relatively large. There are some points where it looks like  $E_\lambda(G_1) = 1$ . These are not the maximum points, so it is possible that the error is very close to 1.

## 14 April 13 - 19

This week I am working on the *The Optimization Landscape for Fitting a Rank-2 Tensor with a Rank-1 Tensor* paper. I added a subsection about the maximum points, and try to combine the  $m = 1$  case and the  $m \geq 2$  case together.